



# New Generalized Fixed Point Results on $S_b$ -Metric Spaces

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## Abstract

Recently,  $S_b$ -metric spaces have been introduced as the generalizations of metric and  $S$ -metric spaces. In this paper, we generalize the classical Banach contraction principle using the theory of a complete  $S_b$ -metric space. Also, we give an application to linear equation systems using the  $S_b$ -metric generated by a metric.

**Keywords:**  $S_b$ -metric space, fixed point, the Banach contraction principle, linear equation.

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## 1. Introduction and mathematical preliminaries

Metric spaces and fixed point theorems are very important in many areas of mathematics. Some generalizations of metric spaces and fixed points of various contractive mappings have been studied extensively. Bakhtin introduced  $b$ -metric spaces as a generalization of metric spaces [5]. Mustafa and Sims defined the concept of a generalized metric space which is called a  $G$ -metric space [17]. Sedghi, Shobe and Aliouche gave the notion of an  $S$ -metric space and proved some fixed-point theorems for a self-mapping on a complete  $S$ -metric space [23]. Aghajani, Abbas and Roshan presented a new type of metric which is called  $G_b$ -metric and studied some properties of this metric [1]. Since then, many authors obtained several fixed-point results in the various generalized metric spaces (see [2, 3, 4, 6, 7, 8, 9, 10, 11, 12, 15, 18, 19, 20, 24, 25] for more details). Also, some applications of fixed point theory were studied on various metric spaces. Several applications of the Banach contraction principle were given in many areas such as integral equations, linear equations, differential equations etc. For example, the present authors investigated some applications on  $S$ -metric spaces (see [21] and [22]).

Recently, the concept of an  $S_b$ -metric space, as a generalization of metric spaces and  $S$ -metric spaces, has been introduced in [26] and a common fixed point theorem for four mappings has been studied on a complete  $S_b$ -metric space. The notion of an  $S_b$ -metric was generalized to the notion of an  $A_b$ -metric in [29]. When  $n = 3$ , the notion of “an  $S_b$ -metric” coincides with the notion of “an  $A_b$ -metric”. Some fixed point theorems were given under different contraction and expansion type conditions (see [29] for more details). After then, some fixed-point results have been studied with various approaches (see [13, 14, 16, 27, 30] for some examples).

In this paper, we consider a complete  $S_b$ -metric space and prove two generalizations of the classical Banach fixed point result. In Section 2, we recall some known definitions. In Section 3, we deal with the notion of an  $S_b$ -metric and investigate some properties of  $S_b$ -metric spaces. We study some relationships between an  $S_b$ -metric and some other metrics. In Section 4, we prove the Banach contraction principle on a complete  $S_b$ -metric space and give a new fixed point theorem as a generalization of the Banach contraction principle with a counterexample. In Section 5, we present an application to linear equations on an  $S_b$ -metric space  $(X, S_1)$ .

Now we recall the following definitions.

**Definition 1.1.** [5] Let  $X$  be a nonempty set,  $b \geq 1$  a given real number and  $d : X \times X \rightarrow [0, \infty)$  a function satisfying the following conditions for all  $x, y, z \in X$  :

(b1)  $d(x, y) = 0$  if and only if  $x = y$ .

(b2)  $d(x, y) = d(y, x)$ .

(b3)  $d(x, z) \leq b[d(x, y) + d(y, z)]$ .

Then the function  $d$  is called a  $b$ -metric on  $X$  and the pair  $(X, d)$  is called a  $b$ -metric space.

**Definition 1.2.** [17] Let  $X$  be a nonempty set and  $G : X \times X \times X \rightarrow [0, \infty)$  a function satisfying the following conditions:

(G1)  $G(x, y, z) = 0$  if  $x = y = z$ .

(G2)  $0 < G(x, x, y)$  for all  $x, y \in X$  with  $x \neq y$ .

(G3)  $G(x, x, y) \leq G(x, y, z)$  for all  $x, y, z \in X$  with  $y \neq z$ .

$$(G4) \quad G(x, y, z) = G(x, z, y) = G(y, z, x) = \dots$$

$$(G5) \quad G(x, y, z) \leq G(x, a, a) + G(a, y, z) \text{ for all } x, y, z, a \in X.$$

Then the function  $G$  is called a generalized metric or a  $G$ -metric on  $X$  and the pair  $(X, G)$  is called a  $G$ -metric space.

**Definition 1.3.** [1] Let  $X$  be a nonempty set,  $b \geq 1$  a given real number and  $G_b : X \times X \times X \rightarrow [0, \infty)$  a function satisfying the following conditions:

$$(G_b1) \quad G_b(x, y, z) = 0 \text{ if } x = y = z.$$

$$(G_b2) \quad 0 < G_b(x, x, y) \text{ for all } x, y \in X \text{ with } x \neq y.$$

$$(G_b3) \quad G_b(x, x, y) \leq G_b(x, y, z) \text{ for all } x, y, z \in X \text{ with } y \neq z.$$

$$(G_b4) \quad G_b(x, y, z) = G_b(x, z, y) = G_b(y, z, x) = \dots$$

$$(G_b5) \quad G_b(x, y, z) \leq b[G_b(x, a, a) + G_b(a, y, z)] \text{ for all } x, y, z, a \in X.$$

Then the function  $G_b$  is called a generalized  $b$ -metric or a  $G_b$ -metric on  $X$  and the pair  $(X, G_b)$  is called a  $G_b$ -metric space.

**Definition 1.4.** [23] Let  $X$  be a nonempty set and  $S : X \times X \times X \rightarrow [0, \infty)$  a function satisfying the following conditions for all  $x, y, z, a \in X$ :

$$(S1) \quad S(x, y, z) = 0 \text{ if and only if } x = y = z.$$

$$(S2) \quad S(x, y, z) \leq S(x, x, a) + S(y, y, a) + S(z, z, a).$$

Then the function  $S$  is called an  $S$ -metric on  $X$  and the pair  $(X, S)$  is called an  $S$ -metric space.

We use the following lemma in the next sections.

**Lemma 1.5.** [23] Let  $(X, S)$  be an  $S$ -metric space. Then we have

$$S(x, x, y) = S(y, y, x).$$

## 2. $S_b$ -Metric spaces

In this section, we recall the notion of an  $S_b$ -metric space and study some properties of this space.

**Definition 2.1.** [26] Let  $X$  be a nonempty set and  $b \geq 1$  a given real number. A function  $S_b : X \times X \times X \rightarrow [0, \infty)$  is said to be  $S_b$ -metric if and only if for all  $x, y, z, a \in X$  the following conditions are satisfied:

$$(S_b1) \quad S_b(x, y, z) = 0 \text{ if and only if } x = y = z,$$

$$(S_b2) \quad S_b(x, y, z) \leq b[S_b(x, x, a) + S_b(y, y, a) + S_b(z, z, a)].$$

The pair  $(X, S_b)$  is called an  $S_b$ -metric space.

We note that  $S_b$ -metric spaces are the generalizations of  $S$ -metric spaces since every  $S$ -metric is an  $S_b$ -metric with  $b = 1$ . But the converse statement is not always true (see [26] for more details). In the following, we give another example of an  $S_b$ -metric which is not an  $S$ -metric on  $X$ .

**Example 2.2.** Let  $X = \mathbb{R}$  and the function  $S_b$  be defined as

$$S_b(x, y, z) = \frac{1}{16}(|x - y| + |y - z| + |x - z|)^2.$$

Then the function  $S_b$  is an  $S_b$ -metric with  $b = 4$ , but it is not an  $S$ -metric. Indeed, for  $x = 4$ ,  $y = 6$ ,  $z = 8$  and  $a = 5$ , we get

$$S_b(4, 6, 8) = 4, \quad S_b(4, 4, 5) = \frac{1}{4}, \quad S_b(6, 6, 5) = \frac{1}{4}, \quad S_b(8, 8, 5) = \frac{9}{4}.$$

Hence we have

$$S_b(4, 6, 8) = 4 \leq S_b(4, 4, 5) + S_b(6, 6, 5) + S_b(8, 8, 5) = \frac{11}{4},$$

which is a contradiction with (S2).

**Definition 2.3.** Let  $(X, S_b)$  be an  $S_b$ -metric space and  $b > 1$ . An  $S_b$ -metric  $S_b$  is called symmetric if

$$S_b(x, x, y) = S_b(y, y, x), \tag{2.1}$$

for all  $x, y \in X$ .

In [28], it was given a definition of an  $S_b$ -metric with the symmetry condition " $S_b(x, x, y) = S_b(y, y, x)$ " (see Definition 1.3 on page 132). However, in the definition of an  $S_b$ -metric, the symmetry condition (2.1) is not necessary. In fact, for  $b = 1$  the  $S_b$ -metric induced to an  $S$ -metric. It is known that the symmetry condition (2.1) is automatically satisfied by an  $S$ -metric (see Lemma 1.5). So Definition 2.1 of an  $S_b$ -metric is more general than given in [28].

We give the following examples of a symmetric  $S_b$ -metric and a non-symmetric  $S_b$ -metric, respectively.

**Example 2.4.** Let  $(X, d)$  be a metric space and the function  $S_b : X \times X \times X \rightarrow [0, \infty)$  defined as

$$S_b(x, y, z) = [d(x, y) + d(y, z) + d(x, z)]^p,$$

for all  $x, y, z \in X$  and  $p > 1$ . Then it can be easily seen that  $S_b$  is an  $S_b$ -metric on  $X$ . Also the function  $S_b$  satisfies the symmetry condition (2.1).

**Example 2.5.** Let  $X = \mathbb{R}$  and the function  $S_b : X \times X \times X \rightarrow [0, \infty)$  be defined as

$$\begin{aligned} S_b(0, 0, 1) &= 2, \\ S_b(1, 1, 0) &= 4, \\ S_b(x, y, z) &= 0 \text{ if } x = y = z, \\ S_b(x, y, z) &= 1 \text{ otherwise,} \end{aligned}$$

for all  $x, y, z \in \mathbb{R}$ . Then the function  $S_b$  is an  $S_b$ -metric with  $b \geq 2$  which is not symmetric.

We define some topological concepts in the following:

**Definition 2.6.** Let  $(X, S_b)$  be an  $S_b$ -metric space,  $x \in X$  and  $A, B \subset X$ .

1. We define the distance between the sets  $A$  and  $B$  by

$$S_b(A, B) = \inf\{S_b(x, x, y) : x \in A, y \in B\}.$$

2. We define the distance of the point  $x$  to the set  $A$  by

$$S_b(x, x, A) = \inf\{S_b(x, x, y) : y \in A\}.$$

3. We define the diameter of  $A$  by

$$\delta(A) = \sup\{S_b(x, x, y) : x, y \in A\}.$$

Now we recall the definition of an open ball and a closed ball on  $S_b$ -metric spaces, respectively.

**Definition 2.7.** [26] Let  $(X, S_b)$  be an  $S_b$ -metric space. The open ball  $B_S^b(x, r)$  and the closed ball  $B_S^b[x, r]$  with a center  $x$  and a radius  $r$  are defined by

$$B_S^b(x, r) = \{y \in X : S_b(y, y, x) < r\}$$

and

$$B_S^b[x, r] = \{y \in X : S_b(y, y, x) \leq r\},$$

for  $r > 0$ ,  $x \in X$ , respectively.

**Example 2.8.** Let us consider the  $S_b$ -metric space defined in Example 2.2 as follows:

$$S_b(x, y, z) = \frac{1}{16}(|x - y| + |y - z| + |x - z|)^2,$$

for all  $x, y, z \in \mathbb{R}$ . Then we get

$$B_S^b(0, 2) = \{y \in \mathbb{R} : S_b(y, y, 0) < 2\} = (-2\sqrt{2}, 2\sqrt{2})$$

and

$$B_S^b[0, 2] = \{y \in \mathbb{R} : S_b(y, y, 0) \leq 2\} = [-2\sqrt{2}, 2\sqrt{2}].$$

**Definition 2.9.** Let  $(X, S_b)$  be an  $S_b$ -metric space and  $X' \subset X$ .

1. If there exists an  $r > 0$  such that  $B_S^b(x, r) \subset X'$  for every  $x \in X'$  then  $X'$  is called an open subset of  $X$ .
2. Let  $\tau$  be the set of all  $X' \subset X$  with  $x \in X'$  such that there exists an  $r > 0$  satisfying  $B_S^b(x, r) \subset X'$ . Then  $\tau$  is called the topology induced by the  $S_b$ -metric.
3.  $X'$  is called  $S_b$ -bounded if there exists an  $r > 0$  such that  $S_b(x, x, y) < r$  for all  $x, y \in X'$ . If  $X'$  is  $S_b$ -bounded then we will write  $\delta(X') < \infty$ .

**Definition 2.10.** [26] Let  $(X, S_b)$  be an  $S_b$ -metric space.

1. A sequence  $\{x_n\}$  in  $X$  converges to  $x$  if and only if  $S_b(x_n, x_n, x) \rightarrow 0$  as  $n \rightarrow \infty$ , that is, for each  $\varepsilon > 0$  there exists  $n_0 \in \mathbb{N}$  such that for all  $n \geq n_0$ ,  $S_b(x_n, x_n, x) < \varepsilon$ . It is denoted by

$$\lim_{n \rightarrow \infty} x_n = x.$$

2. A sequence  $\{x_n\}$  in  $X$  is called a Cauchy sequence if for each  $\varepsilon > 0$  there exists  $n_0 \in \mathbb{N}$  such that  $S_b(x_n, x_n, x_m) < \varepsilon$  for each  $n, m \geq n_0$ .
3. The  $S_b$ -metric space  $(X, S_b)$  is said to be complete if every Cauchy sequence is convergent.

Now we investigate some relationships between  $S_b$ -metric and some other metrics. The relationship between a metric and an  $S$ -metric are given in [11] as follows:

**Lemma 2.11.** [11] Let  $(X, d)$  be a metric space. Then the following properties are satisfied:

1.  $S_d(x, y, z) = d(x, z) + d(y, z)$  for all  $x, y, z \in X$  is an  $S$ -metric on  $X$ .
2.  $x_n \rightarrow x$  in  $(X, d)$  if and only if  $x_n \rightarrow x$  in  $(X, S_d)$ .
3.  $\{x_n\}$  is Cauchy in  $(X, d)$  if and only if  $\{x_n\}$  is Cauchy in  $(X, S_d)$ .
4.  $(X, d)$  is complete if and only if  $(X, S_d)$  is complete.

Since every  $S$ -metric is an  $S_b$ -metric, using Lemma 2.11, an  $S_b$ -metric generated by a metric  $d$  is defined as follows:

$$S_b^d(x, y, z) = b[d(x, z) + d(y, z)],$$

for all  $x, y, z \in X$  with  $b \geq 1$ . But there exists an  $S_b$ -metric which is not generated by any metric as seen in the following example.

**Example 2.12.** Let  $X = \mathbb{R}$ . We consider the function  $S : X \times X \times X \rightarrow [0, \infty)$  given in [19] as follows:

$$S(x, y, z) = |x - z| + |x + z - 2y|,$$

for all  $x, y, z \in \mathbb{R}$ . Then  $(X, S)$  is an  $S$ -metric space. Hence  $(X, S)$  is an  $S_b$ -metric space with  $b = 1$ . This metric is not generated by any metric  $d$ .

In the following lemmas, we show that the relationships between a  $b$ -metric and an  $S_b$ -metric.

**Lemma 2.13.** Let  $(X, S_b)$  be an  $S_b$ -metric space,  $S_b$  a symmetric  $S_b$ -metric with  $b \geq 1$  and the function  $d : X \times X \rightarrow [0, \infty)$  defined by

$$d(x, y) = S_b(x, x, y),$$

for all  $x, y \in X$ . Then  $d$  is a  $b$ -metric on  $X$ .

*Proof.* It can be easily seen that the conditions (b1) and (b2) are satisfied. Now we show that the condition (b3) is satisfied. Using the inequality ( $S_b2$ ), we have

$$\begin{aligned} d(x, y) &= S_b(x, x, y) \leq b[2S_b(x, x, z) + S_b(y, y, z)] \\ &= 2bS_b(x, x, z) + bS_b(y, y, z) \end{aligned}$$

and

$$\begin{aligned} d(x, y) &= S_b(y, y, x) \leq b[2S_b(y, y, z) + S_b(x, x, z)] \\ &= 2bS_b(y, y, z) + bS_b(x, x, z). \end{aligned}$$

Hence we obtain

$$d(x, y) \leq \frac{3b}{2}[d(x, z) + d(y, z)],$$

for all  $x, y \in X$ . Then  $d$  is a  $b$ -metric on  $X$  with  $\frac{3b}{2}$ . □

**Lemma 2.14.** Let  $(X, d)$  be a  $b$ -metric space with  $b \geq 1$  and the function  $S_b : X \times X \times X \rightarrow [0, \infty)$  be defined by

$$S_b(x, y, z) = d(x, z) + d(y, z),$$

for all  $x, y, z \in X$ . Then  $S_b$  is an  $S_b$ -metric on  $X$ .

*Proof.* It can be easily verified that the condition ( $S_b1$ ) is satisfied. We prove that the condition ( $S_b2$ ) is satisfied. Using the inequality (b3) we get

$$\begin{aligned} S_b(x, y, z) &= d(x, z) + d(y, z) \\ &\leq b[d(x, a) + d(a, z)] + b[d(y, a) + d(a, z)] \\ &= bd(x, a) + 2bd(a, z) + bd(y, a) \\ &\leq 2bd(x, a) + 2bd(y, a) + 2bd(a, z) \\ &= b[S_b(x, x, a) + S_b(y, y, a) + S_b(z, z, a)], \end{aligned}$$

for all  $x, y, z \in X$ . Then  $S_b$  is an  $S_b$ -metric on  $X$  with  $b$ . □

Now we give the following example to show that there exists an  $S_b$ -metric which is not generated by any  $b$ -metric.

**Example 2.15.** Let  $X = \mathbb{R}$  and define the function  $S_b : X \times X \times X \rightarrow [0, \infty)$

$$S_b(x, y, z) = b(|x - z| + |x + z - 2y|),$$

for all  $x, y, z \in \mathbb{R}$ , where  $b \geq 1$ . Then  $(\mathbb{R}, S_b)$  is an  $S_b$ -metric space. Now we show that there does not exist any  $b$ -metric  $d$  which generates this  $S_b$ -metric. Conversely, assume that there exists a  $b$ -metric  $d$  such that

$$S_b(x, y, z) = d(x, z) + d(y, z),$$

for all  $x, y, z \in \mathbb{R}$ . Then we get

$$S_b(x, x, z) = 2d(x, z) = 2b|x - z| \text{ and } d(x, z) = b|x - z|$$

and

$$S_b(y, y, z) = 2d(y, z) = 2b|y - z| \text{ and } d(y, z) = b|y - z|,$$

for all  $x, y, z \in \mathbb{R}$ . Therefore we obtain

$$b(|x - z| + |x + z - 2y|) = b|x - z| + b|y - z|,$$

which is a contradiction. Consequently, the  $S_b$ -metric can not be generated by any  $b$ -metric.

**Remark 2.16.** Notice that the class of all  $S$ -metrics and the class of all  $G$ -metrics are distinct [6]. Since every  $S$ -metric is an  $S_b$ -metric and every  $G$ -metric is a  $G_b$ -metric then the class of all  $S_b$ -metrics and the class of all  $G_b$ -metrics are distinct.

### 3. Some fixed point results

In this section, we prove the Banach contraction principle on complete  $S_b$ -metric spaces. Then we give a generalization of this principle. We use the following lemma.

**Lemma 3.1.** [26] *Let  $(X, S_b)$  be an  $S_b$ -metric space with  $b \geq 1$ , then we have*

$$S_b(x, x, y) \leq bS_b(y, y, x) \text{ and } S_b(y, y, x) \leq bS_b(x, x, y).$$

**Theorem 3.2.** *Let  $(X, S_b)$  be a complete  $S_b$ -metric space with  $b \geq 1$  and  $T : X \rightarrow X$  a self-mapping satisfying*

$$S_b(Tx, Tx, Ty) \leq hS_b(x, x, y), \quad (3.1)$$

for all  $x, y, z \in X$ , where  $0 \leq h < \frac{1}{b^2}$ . Then  $T$  has a unique fixed point  $x$  in  $X$ .

*Proof.* Let  $T$  satisfies the inequality (3.1) and  $x_0 \in X$ . Then we define the sequence  $\{x_n\}$  by  $x_n = T^n x_0$ . Using the inequality (3.1) and mathematical induction, we obtain

$$S_b(x_n, x_n, x_{n+1}) \leq h^n S_b(x_0, x_0, x_1). \quad (3.2)$$

Since the conditions  $(S_b2)$  and (3.2) are satisfied for all  $n, m \in \mathbb{N}$  with  $m > n$ , using Lemma 3.1 we get

$$\begin{aligned} S_b(x_n, x_n, x_m) &\leq b[2S_b(x_n, x_n, x_{n+1}) + S_b(x_m, x_m, x_{n+1})] \\ &\leq b[2S_b(x_n, x_n, x_{n+1}) + bS_b(x_{n+1}, x_{n+1}, x_m)] \\ &\leq 2bS_b(x_n, x_n, x_{n+1}) + b^3 [2S_b(x_{n+1}, x_{n+1}, x_{n+2}) + S_b(x_m, x_m, x_{n+2})] \\ &\leq 2bS_b(x_n, x_n, x_{n+1}) + b^3 [2S_b(x_{n+1}, x_{n+1}, x_{n+2}) + bS_b(x_{n+2}, x_{n+2}, x_m)] \\ &\leq 2bS_b(x_n, x_n, x_{n+1}) + 2b^3 S_b(x_{n+1}, x_{n+1}, x_{n+2}) + b^4 S_b(x_{n+2}, x_{n+2}, x_m) \\ &\quad \dots \\ &\leq 2bS_b(x_n, x_n, x_{n+1}) + 2b^3 S_b(x_{n+1}, x_{n+1}, x_{n+2}) + \dots + 2b^{2m-2n-1} S_b(x_{m-1}, x_{m-1}, x_m) \\ &\leq (2bh^n + 2b^3 h^{n+1} + \dots + 2b^{2m-2n-1} h^{m-1}) S_b(x_0, x_0, x_1) \\ &\leq 2bh^n (1 + b^2 h + b^4 h^2 + \dots + b^{2m-2n-2} h^{m-n-1}) S_b(x_0, x_0, x_1) \\ &= 2bh^n \frac{1 - b^{2m-2n} h^{m-n}}{1 - b^2 h} S_b(x_0, x_0, x_1) \\ &\leq \frac{2bh^n}{1 - b^2 h} S_b(x_0, x_0, x_1). \end{aligned}$$

Since  $h \in \left[0, \frac{1}{b^2}\right)$ , where  $b \geq 1$ , taking limit for  $n \rightarrow \infty$  then we obtain  $S_b(x_n, x_n, x_m) \rightarrow 0$  and so  $\{x_n\}$  is a Cauchy sequence. Since  $X$  is complete  $S_b$ -metric space there exists  $x \in X$  with  $\lim_{n \rightarrow \infty} x_n = x$ .

Assume that  $Tx \neq x$ . Using the inequality (3.1) we have

$$S_b(Tx, Tx, x_{n+1}) \leq hS_b(x, x, x_n).$$

If we take limit for  $n \rightarrow \infty$ , we get a contradiction as follows:

$$S_b(Tx, Tx, x) \leq hS_b(x, x, x).$$

Hence  $Tx = x$ . Now we show that the fixed point  $x$  is unique. Suppose that  $Tx = x$ ,  $Ty = y$  and  $x \neq y$ . Using the inequality (3.1), we have

$$S_b(Tx, Tx, Ty) = S_b(x, x, y) \leq hS_b(x, x, y).$$

We obtain  $x = y$  since  $h \in \left[0, \frac{1}{b^2}\right)$ . Consequently,  $x$  is a unique fixed point of the self-mapping  $T$ . □

**Remark 3.3.** *If we take  $b = 1$  in Theorem 3.2 then we obtain Theorem 1 in [20].*

**Corollary 3.4.** *Let  $(X, S_b)$  be a complete  $S_b$ -metric space with  $b \geq 1$ ,  $S_b$  symmetric and  $T : X \rightarrow X$  a self-mapping satisfying the inequality (3.1) for all  $x, y, z \in X$ , where  $0 \leq h < \frac{1}{b}$ . Then  $T$  has a fixed point  $x$  in  $X$ .*

*Proof.* In the proof of Theorem 3.2, if we use the symmetry condition (2.1) instead of Lemma 3.1, we obtain

$$\begin{aligned}
 S_b(x_n, x_n, x_m) &\leq b[2S_b(x_n, x_n, x_{n+1}) + S_b(x_m, x_m, x_{n+1})] \\
 &= b[2S_b(x_n, x_n, x_{n+1}) + S_b(x_{n+1}, x_{n+1}, x_m)] \\
 &\leq 2bS_b(x_n, x_n, x_{n+1}) + b^2[2S_b(x_{n+1}, x_{n+1}, x_{n+2}) + S_b(x_m, x_m, x_{n+2})] \\
 &= 2bS_b(x_n, x_n, x_{n+1}) + 2b^2S_b(x_{n+1}, x_{n+1}, x_{n+2}) + b^2S_b(x_{n+2}, x_{n+2}, x_m) \\
 &\dots \\
 &= 2bS_b(x_n, x_n, x_{n+1}) + 2b^2S_b(x_{n+1}, x_{n+1}, x_{n+2}) + \dots + 2b^{m-n}S_b(x_{m-1}, x_{m-1}, x_m) \\
 &\leq (2bh^n + 2b^2h^{n+1} + \dots + 2b^{m-n}h^{m-1})S_b(x_0, x_0, x_1) \\
 &\leq 2bh^n(1 + bh + b^2h^2 + \dots + b^{m-n-1}h^{m-n-1})S_b(x_0, x_0, x_1) \\
 &\leq 2bh^n \frac{1 - b^{m-n}h^{m-n}}{1 - bh} S_b(x_0, x_0, x_1) \\
 &\leq \frac{2bh^n}{1 - hb} S_b(x_0, x_0, x_1).
 \end{aligned}$$

Since  $h \in \left[0, \frac{1}{b}\right)$  with  $b \geq 1$ , the rest of the proof is similar to that in the proof of Theorem 3.2. □

**Example 3.5.** Let  $X = \mathbb{R}$  and consider the  $S_b$ -metric defined in Example 2.2 as follows:

$$S_b(x, y, z) = \frac{1}{16}(|x - y| + |y - z| + |x - z|)^2,$$

for all  $x, y, z \in \mathbb{R}$  with  $b = 4$ . If we define the self-mapping  $T$  of  $\mathbb{R}$  as

$$Tx = \frac{x}{6},$$

for all  $x \in \mathbb{R}$  then  $T$  satisfies the condition of the Banach contraction principle. Indeed, we get

$$S_b(Tx, Tx, Ty) = \frac{|x - y|^2}{144} \leq hS_b(x, x, y) = \frac{|x - y|^2}{72},$$

for all  $x \in \mathbb{R}$  and  $h = \frac{1}{18}$ . Hence  $T$  has a unique fixed point  $x = 0$  in  $\mathbb{R}$ .

Now we give the following theorem as a generalization of the Banach contraction principle on complete  $S_b$ -metric spaces.

**Theorem 3.6.** Let  $(X, S_b)$  be a complete  $S_b$ -metric space with  $b \geq 1$  and  $T$  a self-mapping of  $X$  satisfying the following condition: There exist real numbers  $\alpha_1, \alpha_2$  satisfying  $\alpha_1 + (2b^2 + b)\alpha_2 < 1$  with  $\alpha_1, \alpha_2 \geq 0$  such that

$$S_b(Tx, Tx, Ty) \leq \alpha_1 S_b(x, x, y) + \alpha_2 \max\{S_b(Tx, Tx, x), S_b(Tx, Tx, y), S_b(Ty, Ty, y), S_b(Ty, Ty, x)\}, \tag{3.3}$$

for all  $x, y \in X$ . Then  $T$  has a unique fixed point  $x$  in  $X$ .

*Proof.* Let  $x_0 \in X$  and the sequence  $\{x_n\}$  be defined as follows:

$$Tx_0 = x_1, Tx_1 = x_2, \dots, Tx_n = x_{n+1}, \dots$$

Assume that  $x_n \neq x_{n+1}$  for all  $n$ . Using the condition (3.3), we get

$$\begin{aligned}
 S_b(x_n, x_n, x_{n+1}) &= S_b(Tx_{n-1}, Tx_{n-1}, Tx_n) \leq \alpha_1 S_b(x_{n-1}, x_{n-1}, x_n) \\
 &\quad + \alpha_2 \max\{S_b(x_n, x_n, x_{n-1}), S_b(x_n, x_n, x_n), \\
 &\quad S_b(x_{n+1}, x_{n+1}, x_n), S_b(x_{n+1}, x_{n+1}, x_{n-1})\} \\
 &= \alpha_1 S_b(x_{n-1}, x_{n-1}, x_n) + \alpha_2 \max\{S_b(x_n, x_n, x_{n-1}), \\
 &\quad S_b(x_{n+1}, x_{n+1}, x_n), S_b(x_{n+1}, x_{n+1}, x_{n-1})\}.
 \end{aligned} \tag{3.4}$$

By the condition  $(S_b2)$ , we have

$$S_b(x_{n+1}, x_{n+1}, x_{n-1}) \leq b[2S_b(x_{n+1}, x_{n+1}, x_n) + S_b(x_{n-1}, x_{n-1}, x_n)]. \tag{3.5}$$

Using the conditions (3.4), (3.5) and Lemma 3.1, we obtain

$$\begin{aligned}
 S_b(x_n, x_n, x_{n+1}) &\leq \alpha_1 S_b(x_{n-1}, x_{n-1}, x_n) + \alpha_2 \max\{S_b(x_n, x_n, x_{n-1}), \\
 &\quad S_b(x_{n+1}, x_{n+1}, x_n), 2bS_b(x_{n+1}, x_{n+1}, x_n) + bS_b(x_{n-1}, x_{n-1}, x_n)\} \\
 &\leq \alpha_1 S_b(x_{n-1}, x_{n-1}, x_n) + 2b\alpha_2 S_b(x_{n+1}, x_{n+1}, x_n) \\
 &\quad + b\alpha_2 S_b(x_{n-1}, x_{n-1}, x_n) \\
 &\leq \alpha_1 S_b(x_{n-1}, x_{n-1}, x_n) + 2b^2\alpha_2 S_b(x_n, x_n, x_{n+1}) \\
 &\quad + b\alpha_2 S_b(x_{n-1}, x_{n-1}, x_n)
 \end{aligned}$$

and so

$$(1 - 2b^2\alpha_2)S_b(x_n, x_n, x_{n+1}) \leq (\alpha_1 + b\alpha_2)S_b(x_{n-1}, x_{n-1}, x_n),$$

which implies

$$S_b(x_n, x_n, x_{n+1}) \leq \frac{\alpha_1 + b\alpha_2}{1 - 2b^2\alpha_2} S_b(x_{n-1}, x_{n-1}, x_n). \quad (3.6)$$

Let  $d = \frac{\alpha_1 + b\alpha_2}{1 - 2b^2\alpha_2}$ . Then  $d < 1$  since  $\alpha_1 + (2b^2 + b)\alpha_2 < 1$ . Notice that  $1 - 2b^2\alpha_2 \neq 0$  since  $0 \leq \alpha_2 < \frac{1}{2b^2 + b}$ . Now repeating this process in the inequality (3.6), we get

$$S_b(x_n, x_n, x_{n+1}) \leq d^n S_b(x_0, x_0, x_1). \quad (3.7)$$

We show that the sequence  $\{x_n\}$  is Cauchy. Indeed, for all  $n, m \in \mathbb{N}$ ,  $m > n$ , using the conditions (3.7) and  $(S_b2)$ , we obtain

$$S_b(x_n, x_n, x_m) \leq \frac{2bd^n}{1 - b^2d} S_b(x_0, x_0, x_1).$$

We have  $\lim_{n, m \rightarrow \infty} S_b(x_n, x_n, x_m) = 0$  by the above inequality and so  $\{x_n\}$  is a Cauchy sequence. By the completeness hypothesis, there exists  $x \in X$  such that  $\{x_n\}$  converges to  $x$ . Suppose that  $Tx \neq x$ . Then we have

$$\begin{aligned} S_b(x_n, x_n, Tx) &= S_b(Tx_{n-1}, Tx_{n-1}, Tx) \\ &\leq \alpha_1 S_b(x_{n-1}, x_{n-1}, x) + \alpha_2 \max\{S_b(x_n, x_n, x_{n-1}), \\ &\quad S_b(x_n, x_n, x), S_b(Tx, Tx, x), S_b(Tx, Tx, x_{n-1})\} \end{aligned}$$

and so taking limit for  $n \rightarrow \infty$  and using Lemma 3.1, we get

$$S_b(x, x, Tx) \leq \alpha_2 S_b(Tx, Tx, x) \leq \alpha_2 b S_b(x, x, Tx),$$

which implies  $S_b(Tx, Tx, x) = 0$  and  $Tx = x$  since  $0 \leq \alpha_2 < \frac{1}{2b^2 + b}$ .

Finally we show that the fixed point  $x$  is unique. To do this, we assume that  $x \neq y$  such that  $Tx = x$  and  $Ty = y$ . Using the inequality (3.3) and Lemma 3.1, we have

$$S_b(Tx, Tx, Ty) = S_b(x, x, y) \leq \alpha_1 S_b(x, x, y) + \alpha_2 \max\{S_b(x, x, x), S_b(x, x, y), S_b(y, y, y), S_b(y, y, x)\},$$

which implies  $x = y$  since  $\alpha_1 + b\alpha_2 < 1$ . Then the proof is completed.  $\square$

**Corollary 3.7.** Let  $(X, S_b)$  be a complete  $S_b$ -metric space with  $b \geq 1$ ,  $S_b$  symmetric and  $T$  a self-mapping of  $X$  satisfying the following condition:

There exist real numbers  $\alpha_1, \alpha_2$  satisfying  $\alpha_1 + 3b\alpha_2 < 1$  with  $\alpha_1, \alpha_2 \geq 0$  such that

$$S_b(Tx, Tx, Ty) \leq \alpha_1 S_b(x, x, y) + \alpha_2 \max\{S_b(Tx, Tx, x), S_b(Tx, Tx, y), S_b(Ty, Ty, y), S_b(Ty, Ty, x)\},$$

for all  $x, y \in X$ . Then  $T$  has a unique fixed point  $x$  in  $X$ .

*Proof.* The proof follows easily by using the symmetry condition (2.1) instead of Lemma 3.1 in the proof of Theorem 3.6.  $\square$

**Remark 3.8.** We note that Theorem 3.6 is a generalization of the Banach contraction principle on  $S_b$ -metric spaces. Indeed, if we take  $\alpha_1 < \frac{1}{b^2}$  and  $\alpha_2 = 0$  in Theorem 3.6 we obtain the Banach contraction principle.

Now we give an example of a self-mapping satisfying the conditions of Theorem 3.6 such that the condition of the Banach contraction principle is not satisfied.

**Example 3.9.** We consider the  $S$ -metric space  $(\mathbb{R}, S)$  with

$$S(x, y, z) = |x - z| + |x + z - 2y|,$$

for all  $x, y, z \in \mathbb{R}$  given in [19] and the self-mapping  $T$  of  $\mathbb{R}$  as

$$Tx = \begin{cases} x + 50 & \text{if } |x - 1| = 1 \\ 45 & \text{if } |x - 1| \neq 1 \end{cases},$$

for all  $x \in \mathbb{R}$  defined in [20]. Since every  $S$ -metric space is an  $S_b$ -metric space,  $(\mathbb{R}, S)$  is an  $S_b$ -metric space with  $b = 1$ . Then the inequality (3.3) is satisfied for  $\alpha_1 = 0$  and  $\alpha_2 = \frac{1}{5}$ . Then  $T$  has a unique fixed point  $x = 45$  by Theorem 3.6. But  $T$  does not satisfy the condition of the Banach contraction principle since for  $x = 1, y = 0$  we get

$$S(Tx, Tx, Ty) = 10 \leq hS(x, x, y) = 2h,$$

which is a contradiction with  $h < 1$ .

#### 4. An application of the Banach contraction to linear equations

In this section, we give an application of the Banach contraction principle on  $S_b$ -metric spaces to linear equations. To do this, we consider the  $S_b$ -metric space generated by

$$d_1(x, y) = \sum_{i=1}^n |x_i - y_i|,$$

for all  $x, y \in \mathbb{R}^n$ . We note that the symmetry condition (2.1) is not necessary in the following example.

**Example 4.1.** Let  $X = \mathbb{R}^n$  be an  $S_b$ -metric space with the  $S_b$ -metric defined by

$$S_1(x, y, z) = \sum_{i=1}^n |x_i - z_i| + \sum_{i=1}^n |y_i - z_i|,$$

for all  $x, y, z \in \mathbb{R}^n$ , where  $b = 1$ . If

$$\sum_{i=1}^n |a_{ij}| \leq h < 1, \quad (1 \leq j \leq n)$$

then the system of linear equations

$$\begin{aligned} a_{11}x_1 + a_{12}x_2 + \cdots + a_{1n}x_n &= b_1 \\ a_{21}x_1 + a_{22}x_2 + \cdots + a_{2n}x_n &= b_2 \\ &\vdots \\ a_{n1}x_1 + a_{n2}x_2 + \cdots + a_{nn}x_n &= b_n \end{aligned} \quad (4.1)$$

has a unique solution. Let  $T$  be defined by

$$Tx = Ax + b,$$

where  $x, b \in \mathbb{R}^n$  and

$$A = \begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \cdots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{pmatrix}.$$

Now we show that the self-mapping satisfies the contraction of the Banach contraction principle. For  $x, y \in \mathbb{R}^n$  we get

$$\begin{aligned} S_1(Tx, Tx, Ty) &= 2 \sum_{i=1}^n \left| \sum_{j=1}^n a_{ij}(x_j - y_j) \right| \leq 2 \sum_{i=1}^n \sum_{j=1}^n |a_{ij}| |x_j - y_j| \\ &= 2 \sum_{j=1}^n \sum_{i=1}^n |a_{ij}| |x_j - y_j| = \sum_{j=1}^n 2 |x_j - y_j| \sum_{i=1}^n |a_{ij}| \\ &\leq h S_1(x, x, y). \end{aligned}$$

Then  $T$  satisfies the Banach contractive condition. Using Theorem 3.6, the linear equations system (4.1) has a unique solution.

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